Multi Sensor Anti Drone Systems



The EMSMSADS80 anti-drone system consists of a spectrum detection system, a radar detection system, intelligent camera tracking system, jamming interference system, and control soft wares. For the spectrum detection system, it is combined with radar detection for system verification, which guides the intelligent camera system to detect, track, and identify the target. Once the intelligent camera system confirmed the target is for the drone type, the linked radio interference countermeasure subsystem will start the action to cut off the drone signal and blind the drone's optical sensing device, causing the drone to make an emergency landing or return.

Through the design of two servo turntables, each module is integrated and uniformly controlled by the anti-drone software, giving full play to the advantages of each device, ensuring that each module device works independently while achieving more efficient linkage and precise disposal. The system has a modular design and can flexibly match detection and interference modules according to customer needs, and flexibly select optical configurations to meet the detection, identification, countermeasures and other needs under different usage scenarios.

Feature

- The system has a high degree of integration, can work independently and efficiently link;
- The spectrum detection function is diverse, deal with detection and analysis of drone signals;
- The radar detection performance is advanced, and digital beamforming is provided;
- The intelligent camera system is intuitive and accurate, and the high-precision servo control ensures stable tracking;
- The combination of soft and hard suppression interference, the integration of interference deception and laser blinding realizes soft and hard killing strikes;
- Modular design, independent splitting and installation of subsystems, and flexible matching; Easy
 installation, wide application, reduced cost, simplified system calibration and debugging, and oneclick achievement.

Technical specification

Model No.	EMSMSADS80		
Distance	For the target of DJI phamtom 4 RF detector≥5km Radar ≥5Km; Camera detection≥5km, Track distance≥4km; Jamming distance≥5Km, Deception distance: ≥5Km; Laser blinding: ≥1Km;		
RF detection	Detection recognition frequency range: 300MHz \sim 6000MHz; Detection frequency: 845MHz \sim 915MHz \sim 1.4GHz \sim 2.4GHz \sim 5.2GHz \sim 5.8GHz; Detection bandwidth: \geq 120MHz; Accuracy: \leq 3 $^{\circ}$ Target detection in one same time: \geq 30 pieces;		
Radar	Working band: X Data refresh data: 2s Target detection: \geqslant 200 pieces Blind area: \leqslant 50m Coverage: Azimuth: $0^{\circ} \sim 360^{\circ}$; Pitch: $0^{\circ} \sim 40^{\circ}$; Altitude: \geqslant 800m Accuracy (RMS): Azimuth: \leqslant 0.4°; Pitch: \leqslant 0.4°; Distance: \leqslant 5m;		
Suppression Interference		Interference countermeasure frequency band: 845MHz/915MHz/1.5GHz/2.4GHz/5.2GHz/5.8GHz Power amplifier ≥50w Navigation deception frequency band: Civilian C/A code frequency band of GPS, GLONASS, BD satellite navigation system; Interference azimuth coverage: 0-360° pitch coverage: -30~60° Interference mode: directional interference Others: Support link interference and navigation interference to work simultaneously Power: ≤1200w	
Intelligent camera	Thermal camera channel	Detector: Cooled focal plane array MCT detector Resolution: 640×512 Lens: 20~450mm, 12x continuous optical zoom Lens control: Electric zoom, manual/auto focus Image enhancement: SDE digital image detail enhancement technology	
	Daylight camera channel	Sensor: $1/1.8"$ target surface starlight-level CMOS, ICR color to black Resolution: 2688×1520 Focal length: $12.5\sim775$ mm HD electric zoom lens Defog: Support photoelectric/electronic dual fog penetration	
	LRF	Distance: ≥3km Wavelength: 1570nm	

	AI • Tracking	Computing power: built-in 16Tops computing power processor Implementation method: front-end embedded hardware recognition and tracking Tracking mode: manual, automatic tracking, support radar linkage Recognition: support classification and recognition of targets such as people, cars, ships, drones, etc. (customers need to assist in providing data sets)	
	Servo platform	Structure: side load, coaxial Horizontal range: N \times 360° continuous rotation, mechanical lock after power failure Pitch range: -30° \sim +60°, with soft limit function, programmable Rotation speed: horizontal 0.01° \sim 100° /s, pitch 0.01° \sim 80° /s Acceleration: horizontal 100° /s2, pitch 100° /s2	
Interface	Network interface: 1 100M/1000M adaptive Ethernet port Power supply: AC220V \pm 20%, 50Hz System power consumption: \leq 3000W Total weight: \leq 260kg		
Software	Integrated control and display: platform integrated design, centralized control, centralized display, more efficient operation Equipment access: support spectrum, radar, optoelectronic, countermeasure equipment access, control, support online status monitoring Situation display: support spectrum detection of drone target information access; support dynamic display of drone target point trace and track information, support radar target track, video recording and synchronous playback. Situation distribution: support spectrum, optoelectronic, radar and countermeasure equipment, target point trace, and other types of information based on two-dimensional comprehensive situation distribution display; support optoelectronic equipment video pop-up window observation and cloud mirror function scheduling; support target track to guide optoelectronic sighting, and each detection information to guide countermeasures. Data fusion: support spectrum and radar track data fusion, 0-20 levels can be set, support spectrum, radar, optoelectronic secondary fusion, sign display. Unmanned: support radar optoelectronic automatic linkage, support single target unmanned, multi-target unmanned; support unmanned automatic strike, strike conditions can be set.		